



AUTOMATIC ALGORITHM CONFIGURATION – METHODS

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Introduction and Overview

- Brief overview on automatic algorithm configuration (AAC)
- Panorama of the methods related to AAC
- Main research lines

- Search space: (heuristic) algorithms solving a problem.
- Objective: find an algorithm of good performance.

Exact problem is *undecidable*.

- Solution: some (truly meta) heuristics which select an algorithm.

Most of the routine part of finding good algorithms can be done better automatically

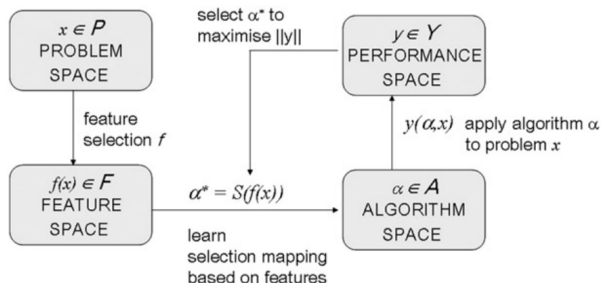
Humans

- usually work iteratively, by trial and error, with small-scale experiments,
- are slow,
- are biased,
- get easily fooled by complex interactions,
- get easily bored.

Let humans do the *creative part*! (For now.)

Rice (1976): The algorithm selection problem

- Four spaces: problems \mathcal{P} , features \mathcal{F} , algorithms \mathcal{A} , performance \mathcal{Y} .
- Feature selection: $f : \mathcal{P} \rightarrow \mathcal{F}$
- Evaluation: $y : \mathcal{A} \times \mathcal{P} \rightarrow \mathcal{Y}$
- Algorithm selection: $S : \mathcal{F} \rightarrow \mathcal{A}$
- Goal: $y(S(f(x)), x) = \max_{a \in \mathcal{A}} \|y(a, x)\|$.



Source: Smith-Miles and Lopes (2012)

- Rice's formulation

$$y(S(f(x)), x) = \max_{a \in \mathcal{A}} ||y(a, x)||$$

is *instance-based* (online selection).

- Note: y can be an expected value, e.g. over seeds.
- For (offline) *algorithm configuration*:

$$y(a) = \max_{a \in \mathcal{A}} ||y(a)||$$

- Now: y is a summary statistic over instances, too.

THE FASTEST AND SHORTEST ALGORITHM
FOR ALL WELL-DEFINED PROBLEMS¹

Where's the problem?

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Key Words

Acceleration, Computational Complexity, Algorithmic Information Theory, Kolmogorov Complexity, Blum's Speed-up Theorem, Levin Search.

- What is the *search space* \mathcal{A} ? How do we represent elements $x \in \mathcal{A}$?
- What is the (exploitable) *structure* of the search space?
- How do we *evaluate* (cheaply!) an algorithm, or compare two algorithms?

- Parameters: *algorithm tuning or calibration*.
Typically: Numerical (real, integer), ordinal, categorical.
- Some selected algorithms: *portfolio methods*.
Typically: online.
- Large class of algorithms: *algorithm configuration or design*.
Typically: Syntax trees, grammars.

These categories are *blurry*.

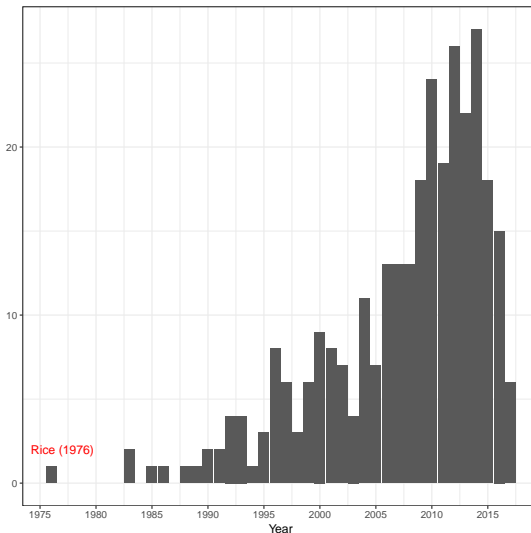
- What is the *distance* of two algorithms?
- What is the *neighbor* of an algorithm?
- What is the *recombination* of two algorithms?
- Is there any *fitness-distance correlation*?

Without structure: can't do better
than *random search* (no free lunch!).

- Theoretical minimum: *time* and solution *quality*.
- Trade-off: *fast*, *anytime*, *best* possible.
- Problems: *instance-dependent* often *stochastic* (= seed-dependent).
- Ideally: Empirical performance models.

Performance evaluation is the
bottleneck and *drives algorithms*

Papers on algorithm selection (N=306)



Source: Kotte (2016)

- Programming by optimization (Hoos 2012; Hoos 2014)
 - Try to *avoid design choices*
 - Make them *explicit*
- Hyper-heuristics (Cowling, Kendall, and Soubeiga 2000)
 - Typically *online*.
- Automatic algorithm configuration (Birattari 2005)

**Features, hardness and
performance models**

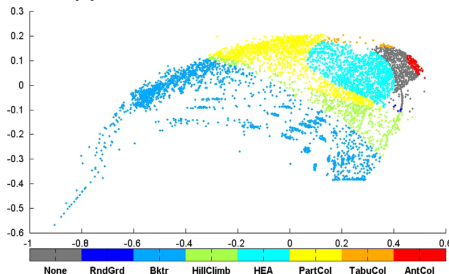
Feature extraction: what?

- **Goals**: reduce data, explain observations, simplify models.
- **Problem-independent**: fitness landscape analysis (e.g. ruggedness, fitness-distance correlation), landmarks.
- **Problem-dependent**: e.g. density in SAT problems, triangle inequality for distances.

Correlation with performance
usually depends on the algorithm

Hardness models

- Techniques: instance classification via **machine learning**
 - e.g. random trees, Bayesian classifiers, decision trees, neural networks.
- Example: **Graph coloring** (Smith-Miles et al. 2014)
 - 18 features, 8 algorithms, GA evolves feature selections
 - Fitness: success of Naive Bayesian classifier to predict being best after projection to 2D with PCA
 - Classifier: Support vector machine



Empirical performance models

- **Assumption**: Practical hardness \Leftrightarrow Empirical performance.
- Solves Rice (1976)'s problem: select algorithm of best predicted performance.
- **Techniques**: again by **machine learning** from examples
- According to Hutter et al. (2014): **random forests** are state of the art \rightsquigarrow SMAC

Search techniques

- **Blackbox function** $f : D \rightarrow \mathbb{R}$, f random variable
- Find $\max_{x \in D} E[f(d)]$ (or other summary statistic).
- Commonly: $D = \mathbb{R}^n$
- Relation to Rice (1976)'s model: for a fixed instance x , function $f(a) = y(a, x)$ is the **black box**.
- For algorithm configuration: $D = \mathcal{A} = A_1 \times \cdots \times A_n$ for n parameters.

- **Model-free**: random search, grid search, direct (pattern) search, genetic programming
Examples: ParamILS, Mesh adaptive direct search, Gender-based genetic algorithm
- **Model-based**: racing (F-Race), surrogates, estimation of distribution
Examples: Sequential Parameter Optimization (SPO), Sequential Model-Based Algorithm Configuration (SMAC), REVAC, Bonesa.

Most are **essentially Blackbox** (i.e. no or light assumptions on algorithmic structure)

- Adaptive mesh refinement, with a current mesh size Δ
- Repeatedly:
 - **Search**: global search on the mesh. On success, coarsen mesh if too fine, continue.
 - **Poll**: local search for an improving point. On success, continue.
 - **Refine**: refine mesh.
- OPAL: Python-implementation of MADS applied to algorithm tuning (Audet, Dang, and Orban 2010).

- Genetic algorithms applied to *evolution of algorithms*.
- Traditional responses in GP:
 - Representation: Syntax trees, often homogeneous (=expressions); grammars.
 - Initialization: grow trees.
 - Crossover: choose random subtrees (biased to internal), exchange them.
 - Mutation: substitute some subtree but a new, random one; change a node.
 - Folk wisdom: larger populations are better (Poli, Langdon, and PcPhee 2008).
- Essentially *same difficulties* as generic problem: representation, modification, evaluation.

- **Individuals**: variable trees of parameters (bounded numerical or categorical), either of competing or non-competing gender.
- **Selection**: Top 10% competing mate with random non-competing individual.
- **Crossover**: Uniform, tree-based, with higher correlation of variables in subtrees.
- **Mutation**: With fixed probability 0.1 uniform for categorical, Gaussian for numerical parameters.
- **Evaluation**: Racing on N random instances, N increasing over runtime.
- Claim: better than ParamILS.

- **Other names:** metamodels, response surface models, approximation model, cheap models.
- Substitute costly evaluation of f by a surrogate function s .
- Surrogate s is a **simplified model**.
- Repeatedly: find a minimizer x of s , evaluate $f(x)$, update surrogate s .
- Sequential Model-Based Algorithm Configuration (SMAC) (Hutter, Hoos, and Leyton-Brown 2011) is a surrogate method using random forests.

- An example of an **estimation of distribution** algorithm.
- **Steady-state** evolution of a population of parameter settings: recombine n best, replace oldest.
- **Recombination**: uniform scanning.
- **Mutation**: independent for each parameter. Sort values of all parents, substitute value in child x by $U[l, u]$, where l is the value of the h -th predecessor and u the value of the h -th successor of x . ($h \approx n/10$)
- REVAC maximizes the entropy of the marginal distributions of each parameter.

Conclusion

- There's *nothing new* under the sun.
- But we find a *lot of different names* for similar ideas.
- There's *nothing specific* to meta-heuristics (model, search space structure).
- How can we *evaluate more aggressively*?



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