



GRAPH SEARCHES

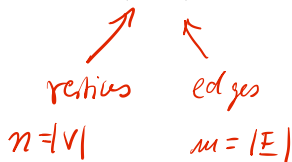
Marcus Ritt

CMP 601 – Algorithms and Theory of Computation —

April 2020

1. Review
2. Depth-first search
3. Implementation aspects
4. Bipartiteness

- We're exploring an *undirected* graph $G = (V, E)$.

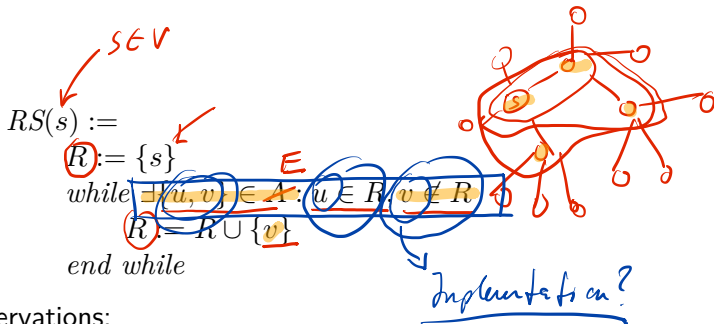

vertices $n = |V|$ edges $m = |E|$

$BFS(s) :=$ *← starting vertex s = v*
 $T := \emptyset$
 $L_0 := \{s\}$ *i = 0*
 while $L_i \neq \emptyset$
 $L_{i+1} := \{v \in V \mid \{u, v\} \in A, u \in L_i, v \text{ unseen}\}$
 $T := T \cup \{\{u, v\} \mid \{u, v\} \in A, u \in L_i, v \text{ unseen}\}$
 $i := i + 1$
 end while

Observations:

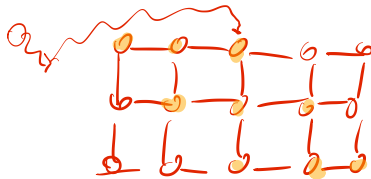
BFS(s) explores the conn. component of s

- L_i contains nodes at distance i from s . An s - t path exists, if $t \in L_i$ for some i .
- BFS defines a BFS tree T .
- Proposition: If $x, y \in T$ and $x \in L_i, y \in L_j$: $|i - j| \leq 1$.



Observations:

- Proposition: R is the connect component of s .



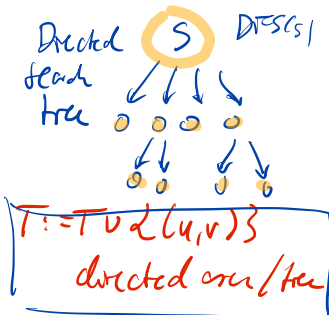
$v \in V$

$DFS(v) :=$
 $visited(v) := true$
 for $u \in N(v) | visited(u) = false$ do
 $\triangleright DFS(u)$

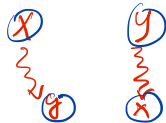
$T \leftarrow T \cup \{(v, u)\}$

Observations:

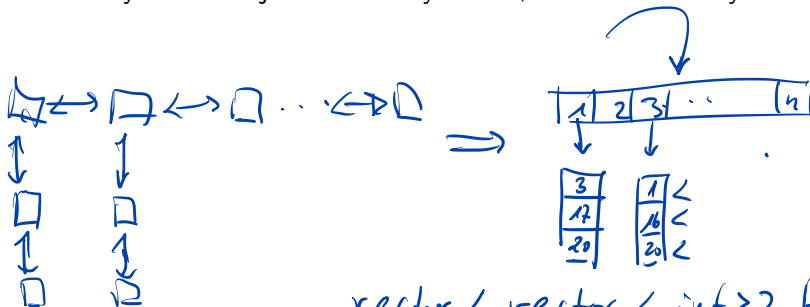
undirected edge



- Again $DFS(s)$ defines a tree T : every vertex except s has exactly one incoming arc, and T is connected, by construction.
- All explored vertices during $DFS(s)$ are descendants of s .
- Proposition:** If $\{x, y\} \in E$ and $\{x, y\} \notin T$ then x is ancestor of y or vice versa.



- Why don't we just visit every vertex, in some arbitrary order?



vector < vector < int?? A;

Adj. matrix

A

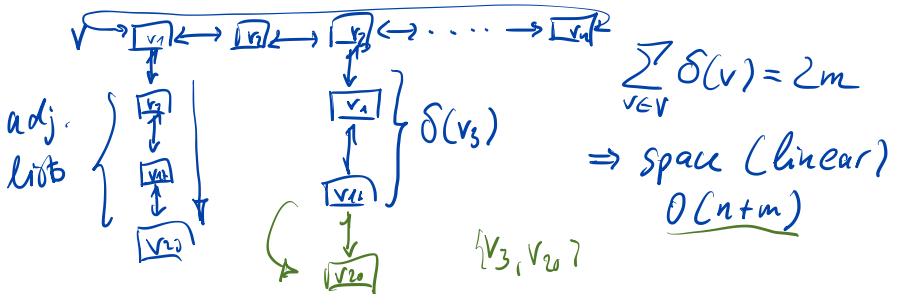
	1	2	3	...	7	n
1						
2		1				2
3			1			2
...						2
7					1	2
n						2

space

$\{3, 2\} \in E$
 $A[2,3] = A[3,2] = 1$

$\{u, v\} \in E$? $A[u, v] = 1$?
 $O(\delta(v))$ $O(1)$
 for $u \in N(v)$: • for $u = 1 \dots n$
 if $A[u, v]$:
 • $O(n)$
 • $O(\delta(v))$

- Adjacency matrices
- Adjacency lists or vectors, forward or backward stars





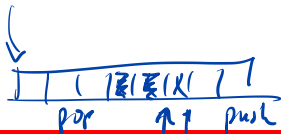
- A **queue**: processes items in order (FIFO)
 - **Enqueue** (**push**): add an element at one end
 - **Dequeue** (**pop**): remove an element from the other end
- A **stack**: processes items in reverse order of addition (**LIFO**)
 - **Push**: add an element to the top
 - **Pop**: remove an element from the top
- How do we implement these data structures?
- What do these operations cost?

Stacks: *rector*



push/pop $O(1)$
search $O(n)$

Queues:



push/pop $O(1)$

3

IMPLEMENTATION ASPECTS

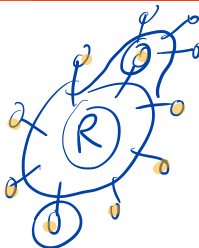
Implementation of searches

GRAPH SEARCHES

linear time
 $\rightarrow O(n+m)$

- **BFS**: maintain vertices in a queue
- **DFS**: maintain vertices in a stack (non-recursive)
- How do we implement a random search?
- What does it cost?

fringe vertex:
 unexplored vertex
 connected to a
 already explored vertex



fringe
 vertices

Queue or stack or
vector of fringe vertices¹⁰

A undirected graph $G = (V, E)$ such that

- Vertices have two parts: $V = L \cup R$, $L \cap R = \emptyset$
- Edges only between parts: $E \subseteq \{\{u, v\} \mid u \in L, v \in R\}$

The following is equivalent:

1. G is bipartite
2. G has no odd cycles
3. G has no edges connecting vertices in the same layer of the BFS tree.