



GREEDY ALGORITHMS, PART 3: MINIMUM SPANNING TREES

Marcus Ritt

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1. Minimum spanning trees

The problem

- Undirected graph $G = (V, E, c)$ with costs $c : E \rightarrow \mathbb{R}_+$

- **Definition:** A **spanning** subgraph is one that connects all vertices.

- **Want:** Minimum cost spanning subgraph.

- **Observation:** This must be a tree.

Suppose we have a **cycle**: we can remove an edge, and the graph stays connected. We end up with a connected, cycle-free graph, by definition a tree.

- Thus: we can **focus on minimum spanning trees**.
- If the graph is **connected**: application to all components yields a **minimum spanning forest**.

Tree (acyclic graph)

Forest: collection of trees

$$T_1 = (V_1, E_1)$$

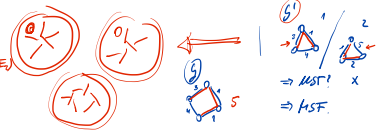
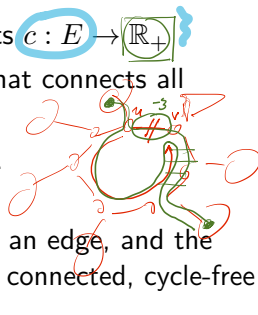
$$T_2 = (V_2, E_2)$$

$$V_1 \cap V_2 = \emptyset$$

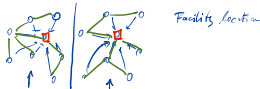
$$T_1 \cup T_2 =$$

$$U \mathcal{F} = (V_1 \cup V_2, E_1 \cup E_2)$$

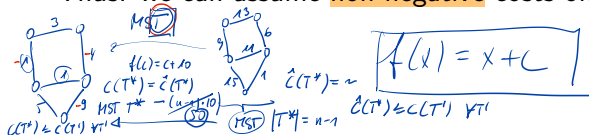
forest



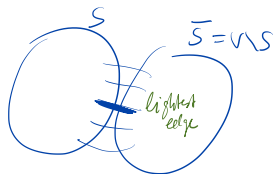
Related problems



- **Observation:** Reduction to a tree fails when we have negative costs.
- For negative costs the minimum cost spanning subgraphs could contain all edges!
- On the other hand: when we **require trees**, we have exactly $n - 1$ edges, and every **monotone transformation** of the costs maintains minimality. *→ Alg. work even w/ negative costs*
- In particular: **linear** transformations, and even more particular: **addition** of a constant. $c_1 \leq c_2 \Rightarrow f(c_1) \leq f(c_2)$ $\uparrow \log, \downarrow x^2$
- Thus: we can assume **non-negative** costs on trees. $\log(\prod_{e \in T} c_e) = \sum_{e \in T} \log c_e$

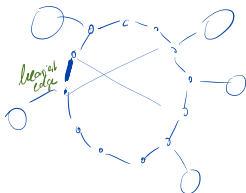


- We can assume that all edge costs are different.
- All algorithms will work when edge costs are the same.
- Argument: by **perturbation** of the costs.

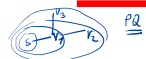


Cut property For every cut $(S, \bar{S})$: the lightest cut edge is part of the MST

Cycle property For every cycle C : the heaviest cycle edge is not part of the MST



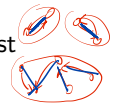
- Grow a component S (**Prim**, Jarník)



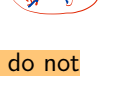
 - Starting from $S = \{s\}$, repeatedly add lightest $(S, \bar{S})$ -edge
 - Using a priority queue: $O(n \log n + m)$
- Merge components (Kruskal)



 - Starting from sets $\{v\}$ for all $v \in V$, process edges in ~~non-decreasing~~ ^{increasing} cost, add edges that connect components
 - Using a **union/find** data structure: $O(m \log n)$
- Parallel merge (Borůvka)**



 - Starting from sets $\{v\}$ for all $v \in V$, repeatedly find lightest cut edges for all components, add all edges
 - Takes $\log_2 n$ iterations, (number of components is at least halved) in $O(m)$.
- Reverse delete (**Kruskal**)



 - Process edges in ~~non-increasing~~ ^{decreasing} cost, **remove edges that do not disconnect the graph.**
 - Check can be done in $O(\log n (\log \log n)^3)$ (Thorup 2000).